



### **CONTACT INFO:** farias02@ucm.es

# INTRODUCTION



Studies with awake animals are needed in order to avoid the effects of anesthesia on PET response in the brain and to perform simultaneous physiological and psychological studies.

The detection of external motion based on the optical tracking of markers placed on the surface of the skin of the patient, have been

# Awake preclinical brain PET imaging based on point sources

<u>F. Arias-Valcayo<sup>1</sup></u>, Joaquín L. Herraiz<sup>1,2</sup>, P. Galve<sup>1</sup>, J. J. Vaquero<sup>3,4</sup>, M. Desco<sup>4</sup>,

José M. Udías<sup>1,2</sup>

<sup>1</sup>Grupo de Física Nuclear and IPARCOS, Dpto. Física Atómica, Molecular y Nuclear, Universidad Complutense de Madrid, CEI

Moncloa, Madrid, Spain

<sup>2</sup>Health Research Institute of the Hospital Clínico San Carlos (IdSSC), Madrid, Spain

<sup>3</sup>Universidad Carlos III de Madrid, Departamento de Bioingeniería e Ingeniería Aerospacial, Madrid, Spain





**Grupo de Física Nuclear. UCM** 

proposed.



In In order to avoid the requirement of additional hardware, we propose to use several external relatively-low activity sources to register the reconstructed images from the motion-free fragments of the acquisition.

## METHODS

### **Motion-free frames** identification

Position of the centroid of all acquired LORs is obtained every 50 ms.



### **Motion characterization**

To improve the precision of the motion characterization, motion-free frames are split into short frames (25 ms in the figure below).

#### **Motion-free frames**



Short frames

The four <sup>18</sup>F markers attached on the rat head were located in these images and they were used to register the images with a reference one.



Motion compensation

We

Fig 1. Position of the centroid of the detected LORs. Each green area is a motion-free frame that will be used for the reconstruction. Red areas are the time lapses where the movement is significant and are rejected.

### RESULTS

Anesthesia Awake Max. Min.

Awake rat injected with 600 µCi and four <sup>18</sup>F sources attached in its head.

70% of the acquired events are used in the reconstruction.

**Resolution** of the image in both cases is  $1.00 \pm 0.05$  mm

apply

compensation

iteration.

Frame 2 after motion compensation

scanner crystals in order

to use every count in each

the

to

Frame 2

Time

Frame 1



motion

the

#### In this work only **rigid transformation** were considered, which is a reasonable assumption for head imaging.



After LOR relocation the acquisition is reconstructed using 15 iterations of an EMML-MAP algorithm implemented in-house using PGI CUDA Fortran Compiler.

### CONCLUSIONS







Motion-free frames are correctly identificated

Centroid method is really fast and robust Resolution is comparable to motion-free acquisitions

#### References

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